

Note: Slides complement the discussion in class



Bellman-Ford Algorithm Shortest paths with negative weights

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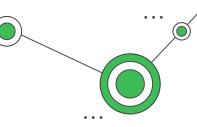
UI Bellman-Ford Algorithm

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Shortest paths with negative weights

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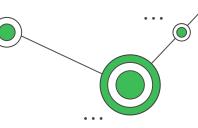


Wanna make an easy profit? Use graphs!

If you have USD \$10,000...

- How many Swiss francs (CHF) can you buy?
- How many Euros (EUR) can you buy?
- How could you exchange money and make a profit?

	USD	EUR	GBP	CHF	CAD
USD	1	0.741	0.657	1.061	1.005
EUR	1.349	1	0.888	1.433	1.366
GBP	1.521	1.126	1	1.614	1.538
CHF	0.942	0.698	0.619	1	0.953
CAD	0.995	0.732	0.650	1.049	1

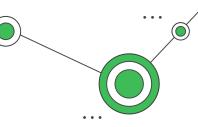


<u>Buy USD 10,000 in EUR</u>: 10,000 * 0.741 Now you have **EUR 7,410**.

<u>Buy CAD with your EUR</u>: 7,410 * 1.366 You get **CAD 10,122**.

<u>BUY USD with your CAD</u>: 10,122 * 0.995 You get **USD 10,071 (Profit!)**

	USD	EUR	GBP	CHF	CAD
USD	1	0.741	0.657	1.061	1.005
EUR	1.349	1	0.888	1.433	1.366
GBP	1.521	1.126	1	1.614	1.538
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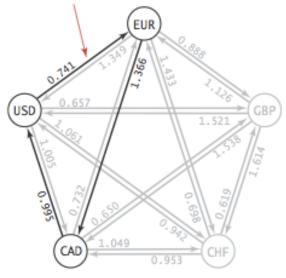


Challenges:

- 1. Understand the problem in terms of graphs.
- 2. Find a cycle in the graph such that it "always increases its weight". Is that even possible?

	USD	EUR	GBP	CHF	CAD
USD	1	0.741	0.657	1.061	1.005
EUR	1.349	1	0.888	1.433	1.366
GBP	1.521	1.126	1	1.614	1.538
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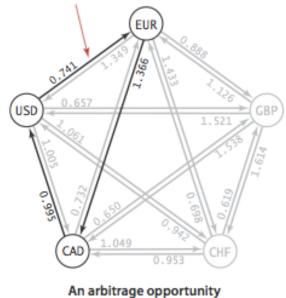
0.741 * 1.366 * .995 = 1.00714497



An arbitrage opportunity

	USD	EUR	GBP	CHF	CAD
USD	1	0.741	0.657	1.061	1.005
EUR	1.349	1	0.888	1.433	1.366
GBP	1.521	1.126	1	1.614	1.538
CHF	0.942	0.698	0.619	1	0.953
CAD	0.995	0.732	0.650	1.049	1

0.741 * 1.366 * .995 = 1.00714497



Transform the problem: Let u, v, w be the weights of three edges forming a cycle in a graph.

Goal: uvw > 1

uvw > 1 log(uvw) > log(1) log(u) + log(v) + log(w) > 0 -1(log(u) + log(v) + log(w)) < 0-log(u) - log(v) - log(w) < 0

Now the problem is to find a negative weight cycle in the graph. Let's use the **<u>Bellman-Ford algorithm</u>**.

. .

Richard Bellman. "On a Routing Problem." Quarterly of Applied Mathematics, vol. 16, no. 1, pp. 87-90, 1958.

. . .

Lester R. Ford, Jr. "Network Flow Theory." RAND Corporation, P-923, 1956.

1958]

RICHARD BELLMAN

ON A ROUTING PROBLEM*

By RICHARD BELLMAN (The RAND Corporation)

Summary. Given a set of N cities, with every two linked by a road, and the times required to traverse these roads, we wish to determine the path from one given city to another given city which minimizes the travel time. The times are not directly proportional to the distances due to varying quality of roads and varying quantities of traffic.

The functional equation technique of dynamic programming, combined with approximation in policy space, yields an iterative algorithm which converges after at most (N-1) iterations.

 Introduction. The problem we wish to treat is a combinatorial one involving the determination of an optimal route from one point to another. These problems are usually difficult when we allow a continuum, and when we admit only a discrete set of paths, as we shall do below, they are notoriously so.

The purpose of this paper is to show that the functional equation technique of dynamic programming, [1, 2], combined with the concept of approximation in policy space, yields a method of successive approximations which is readily accessible to either hand or machine computation for problems of realistic magnitude. The methou is distinguished by the fact that it is a method of exhaustion, i.e. it converges after a finite number of iterations, bounded in advance.

2. Formulation. Consider a set of N cities, numbered in some arbitrary fashion from 1 to N, with every two linked by a direct road. The time required to travel from i to j is not directly proportional to the distance between i and j, due to road conditions and traffic. Given the matrix $T = (l_{ii})$, not necessarily symmetric, where l_{ii} is the time required to travel from i to j, we wish to trace a path between 1 and N which consumes minimum time.

Since there are only a finite number of paths available, the problem reduces to choosing the smallest from a finite set of numbers. This direct, or enumerative, approach is impossible to execute, however, for values of N of the order of magnitude of 20.

We shall construct a search technique which greatly reduces the time required to find minimal paths.

3. Functional equation approach. Let us now introduce a dynamic programming approach. Let

with $f_N = 0$.

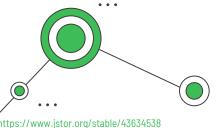
Employing the principle of optimality, we see that the f_i satisfy the nonlinear system of equations

$$f_i = \min_{i \neq i} [t_{ii} + f_i], \quad i = 1, 2, \cdots, N - 1,$$

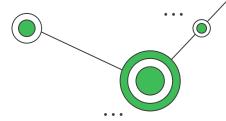
 $f_N = 0.$
(3.2)

*Received January 30, 1957.

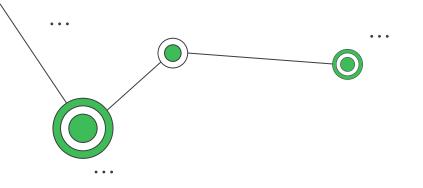
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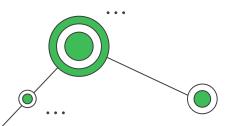
Bellman-Ford Algorithm



- 1. Given a digraph $G = \{V, E\}$ and a source vertex $v \in V$, Bellman-Ford's algorithm finds the shortest path from v to every other vertex in the digraph.
- 2. Bellman-Ford's algorithm works on any weighted digraph (even with negative weights).
- 3. The last pass through the edges will determine if there are negative weight cycles.

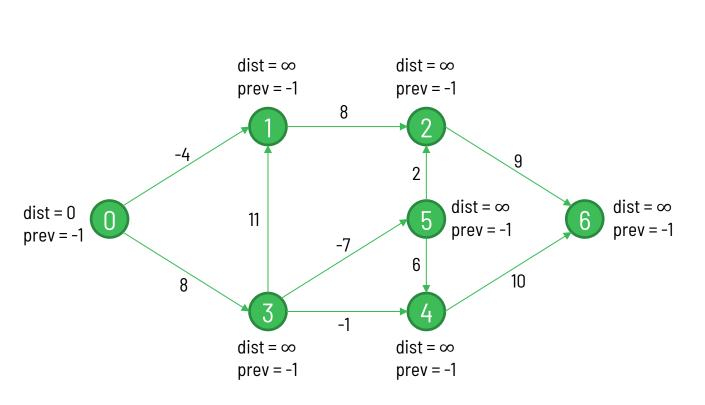


Bellman-Ford Algorithm

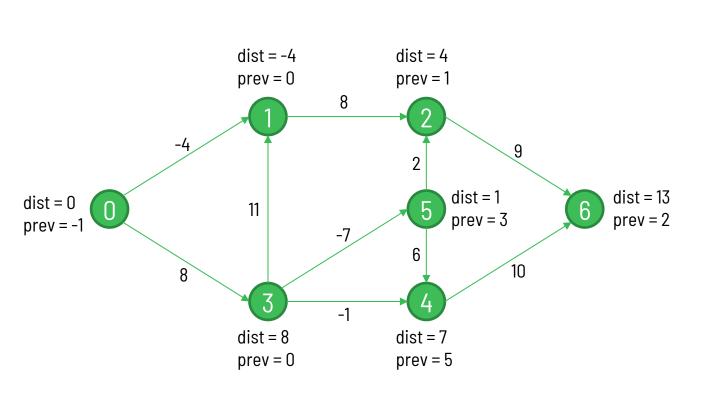


```
algorithm BellmanFord(G(V, E), s \in V)
   let dist:V \to \mathbb{Z}
   let prev:V \rightarrow V
   for each v \in V do
       dist[v] \leftarrow \infty
       prev[v] \leftarrow -1
   end for
   dist[s] \leftarrow 0
   for i from 1 to |V| - 1 do
       for each e = (u, v) \in E do
           d \leftarrow dist[u] + weight(e)
           if d < dist[v] then</pre>
               dist[v] \leftarrow d
               prev[v] \leftarrow u
           end if
       end for
   end for
   for each e = (u, v) \in E do
       if dist[u] + weight(e) < dist[v] then
           error "Negative Weight Cycle"
       end if
   end for
```

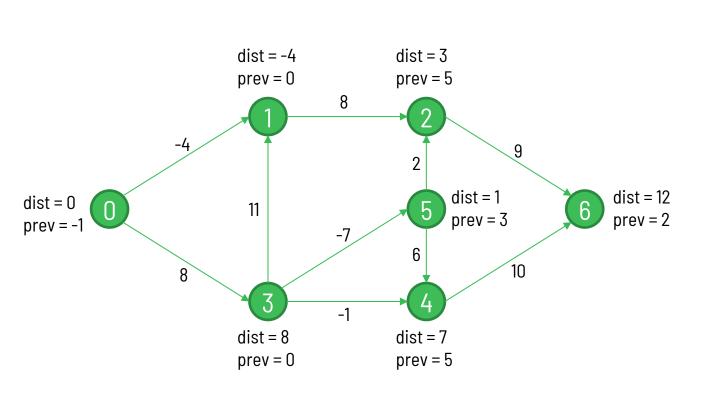
```
return dist, prev
end algorithm
```



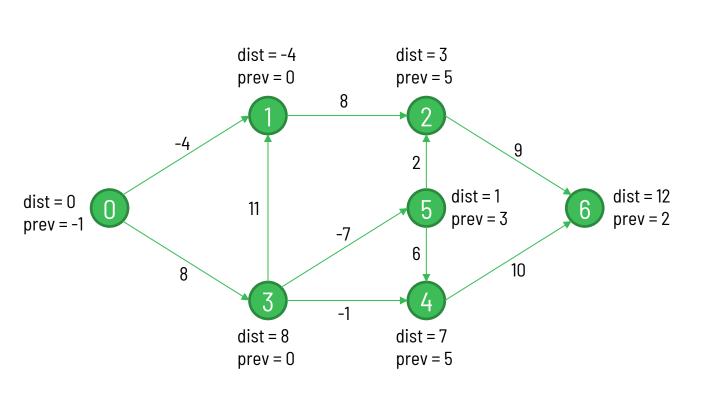
Edge	i = 1	i = 2	i = 3
(0, 1)			
(0, 3)			
(1, 2)			
(3, 1)			
(5, 2)			
(3, 5)			
(5, 4)			
(3, 4)			
(4, 6)			
(2, 6)			



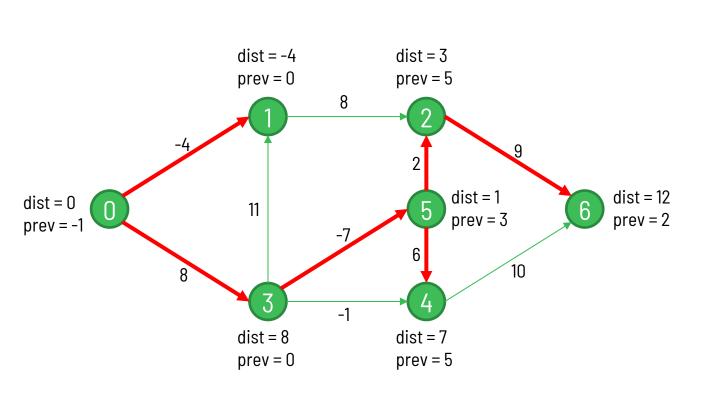
Edge	i = 1	i = 2	i = 3
(0, 1)	\checkmark		
(0, 3)	\checkmark		
(1, 2)	\checkmark		
(3, 1)	Х		
(5, 2)	Х		
(3, 5)	\checkmark		
(5, 4)	\checkmark		
(3, 4)	Х		
(4, 6)	\checkmark		
(2, 6)	\checkmark		



Edge	i = 1	i = 2	i = 3
(0, 1)	\checkmark	Х	
(0, 3)	\checkmark	Х	
(1, 2)	\checkmark	Х	
(3, 1)	Х	Х	
(5, 2)	Х	\checkmark	
(3, 5)	\checkmark	Х	
(5, 4)	\checkmark	Х	
(3, 4)	Х	Х	
(4, 6)	\checkmark	Х	
(2, 6)	\checkmark	\checkmark	



Edge	i = 1	i = 2	i = 3
(0, 1)	\checkmark	Х	Х
(0, 3)	\checkmark	Х	Х
(1, 2)	\checkmark	Х	Х
(3, 1)	Х	Х	Х
(5, 2)	Х	\checkmark	Х
(3, 5)	\checkmark	Х	Х
(5, 4)	\checkmark	Х	Х
(3, 4)	Х	Х	Х
(4, 6)	\checkmark	Х	Х
(2, 6)	\checkmark	\checkmark	Х



Edge	i = 1	i = 2	i = 3
(0, 1)	\checkmark	Х	Х
(0, 3)	\checkmark	Х	Х
(1, 2)	\checkmark	Х	Х
(3, 1)	Х	Х	Х
(5, 2)	Х	\checkmark	Х
(3, 5)	\checkmark	Х	Х
(5, 4)	\checkmark	Х	Х
(3, 4)	Х	Х	Х
(4, 6)	\checkmark	Х	Х
(2, 6)	\checkmark	\checkmark	Х



algorithm BellmanFord(G(V, E), $s \in V$)

```
let dist:V \to \mathbb{Z}
let prev:V \rightarrow V
for each v \in V do
   dist[v] \leftarrow \infty
   prev[v] \leftarrow -1
end for
dist[s] \leftarrow 0
for i from 1 to |V| - 1 do
   for each e = (u, v) \in E do
       d \leftarrow dist[u] + weight(e)
       if d < dist[v] then
           dist[v] \leftarrow d
           prev[v] \leftarrow u
       end if
    end for
end for
for each e = (u, v) \in E do
    if dist[u] + weight(e) < dist[v] then
       error "Negative Weight Cycle"
    end if
```

end for

```
return dist, prev
end algorithm
```

Runtime:

- Initializing arrays: O(|V|)
- Resetting values in the arrays (aka. Edge relaxation): O(|V||E|)
- Checking for negative weight cycles:
 O(|E|)

Bellman-Ford's Runtime: O(|V||E|)

We're Done!

Do you have any questions?

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